

PreMicrostet.project - CODESYS

File Edit View Project Build Online Debug Tools Window Help

Devices

PreMicrostet

Device (CODESYS Control for Raspberry Pi)

PLC Logic

Application

GVL

Library Manager

INITTASK (PRG)

Ipo (PRG)

Move_Ctrl (PRG)

POU (PRG)

Task Configuration

BusTask

EtherCAT_Master.EtherCAT_Task

Ipo

INITTASK

Move_Ctrl

POU

SoftMotion General Axis Pool

EtherCAT_Master (EtherCAT Master)

FPRO (FPRO EtherCAT Drive (CoE))

DriveX (SM_Drive_GenericDSP402)

GPIOs_A_B (GPIOs A/B)

I-C

SPI

Onewire

Camera device

GPIOs_A_B

GVL

Ipo

Move_Ctrl

Move_Ctrl

EtherCAT_Master

POU

FPRO

DriveX

Edit IO mappi

Find

Filter Show all

Variable	Mapping	Channel	Address
ControlWord		ControlWord	%QW0
Modes of operation		Modes of operation	%QB2
Target position		Target position	%QD1
Profile velocity		Profile velocity	%QD2
Target Velocity		Target Velocity	%QD3
Data Record 1		Data Record 1	%QD4
Velocity Offset		Velocity Offset	%QD5
Target torque		Target torque	%QW12
Digital Output		Digital Output	%QD7
Torque Offset		Torque Offset	%QW16
Analog output value		Analog output value	%QD9
StatusWord		StatusWord	%IW0
Modes of operation display		Modes of operation display	%IB2
Torque Actual Value		Torque Actual Value	%IW2
Position actual value		Position actual value	%ID2
Velocity actual value		Velocity actual value	%ID3
Current actual value		Current actual value	%IW8
Torque Demand Value		Torque Demand Value	%IW9
Analog Input 1		Analog Input 1	%IW10
Analog Input 2		Analog Input 2	%IW11

Digital Output

Reset Mapping

Always update variables: Enabled 2 (always in bus cycle task)

IEC Objects

Variable	Mapping	Type
FPRO		ETCSlave

Create new variable

Map to existing variable

Last build: 0 0 0 Precompile: Current user: (nobody)